

Road Extraction on Remote Sensing Imagery

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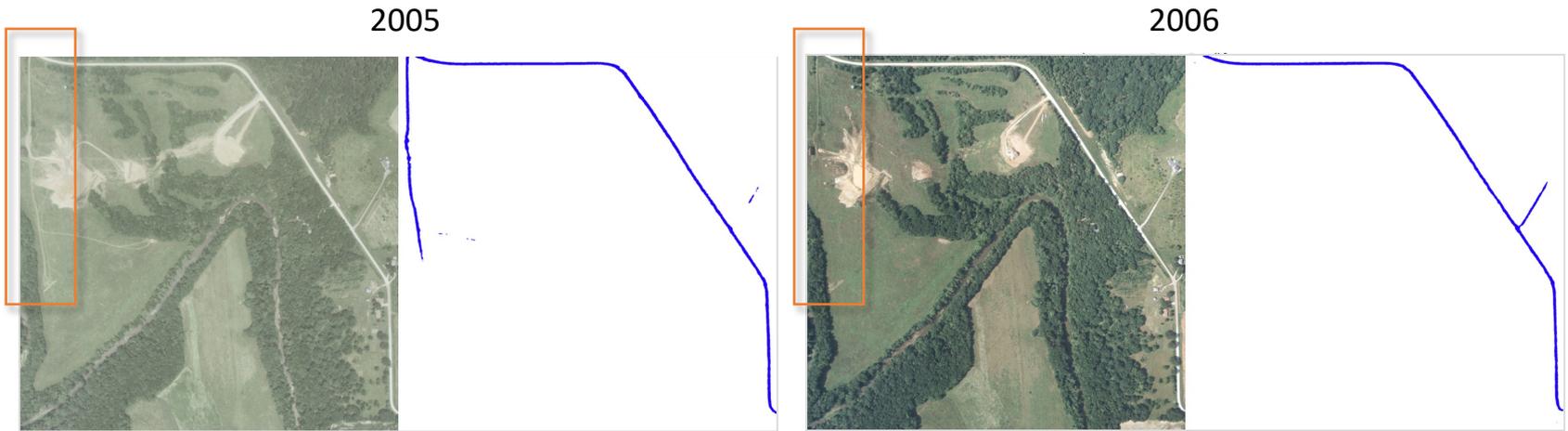
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I. Project overview

Goal:

Automated road extraction and change detection



Classification task is non-trivial

Road covered by trees

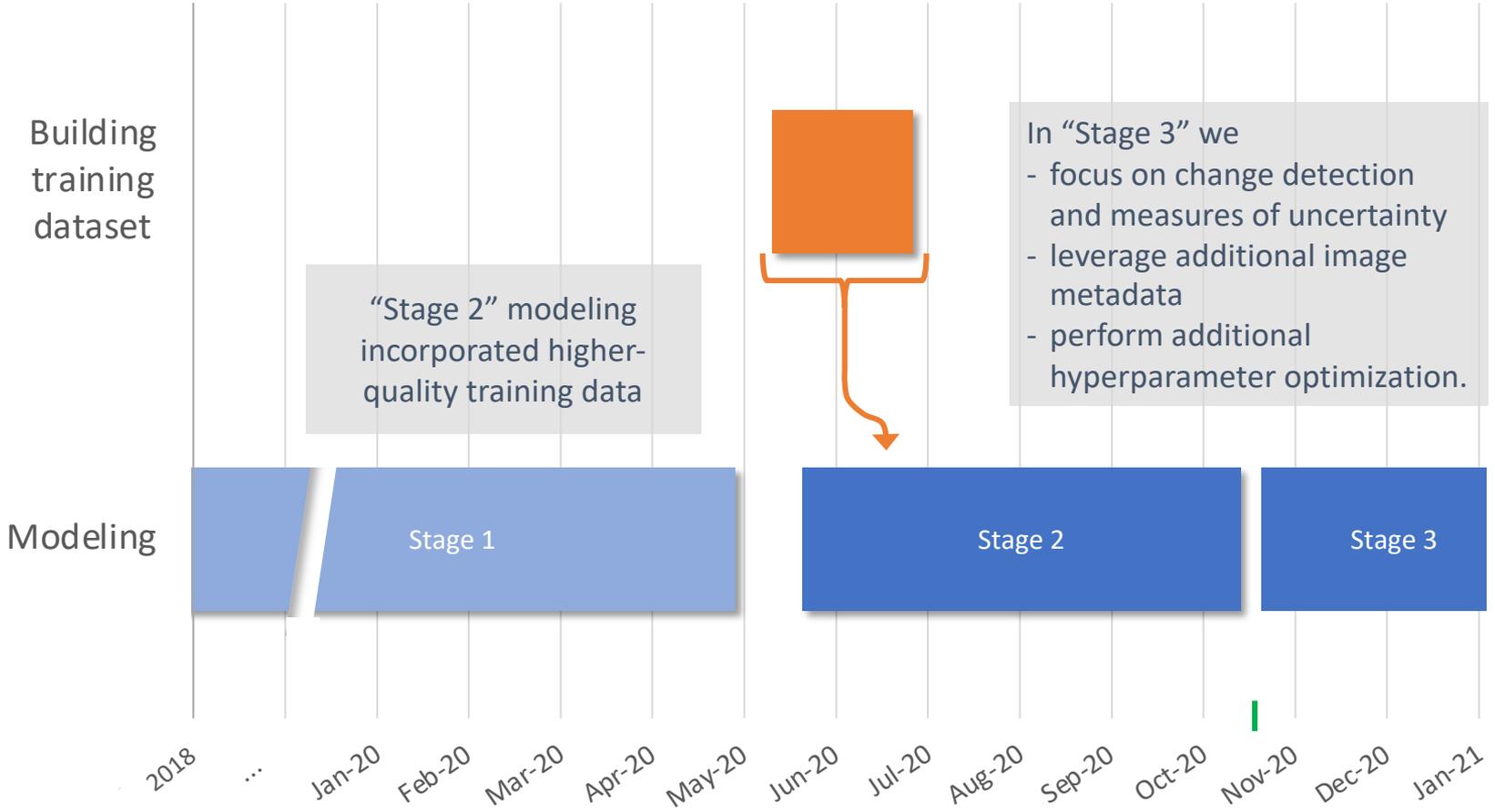


Not all paved areas are roads



The classifier should take into consideration a sort of context \Rightarrow neural nets

Project timeline



Results summary

We have achieved $\approx 80\%$ dice score with models trained on 30k images

Model	Dice score
AD-LinkNet	0.78
UNet	0.78
GLNet	0.72



We are now extracting roads on 2005-2017 satellite time series



2005

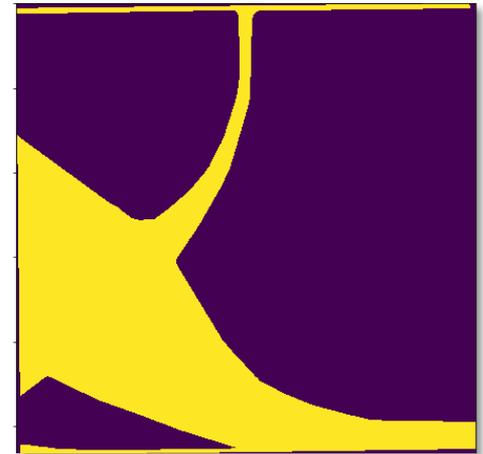
2017

II. Building a training dataset

Why use Google dataset?

The current NRI dataset consisting of 5k remote sensing image and road annotation image pairs ...

- is **small** considering task difficulty and modeling limitations,
- contains numerous instances of **poorly annotated** roads from machine learning perspective (see example right), and
- is kept in a specialized server to ensure **confidentiality** but which has limited computing capacity.



Problematic
image type:
coarse annotation

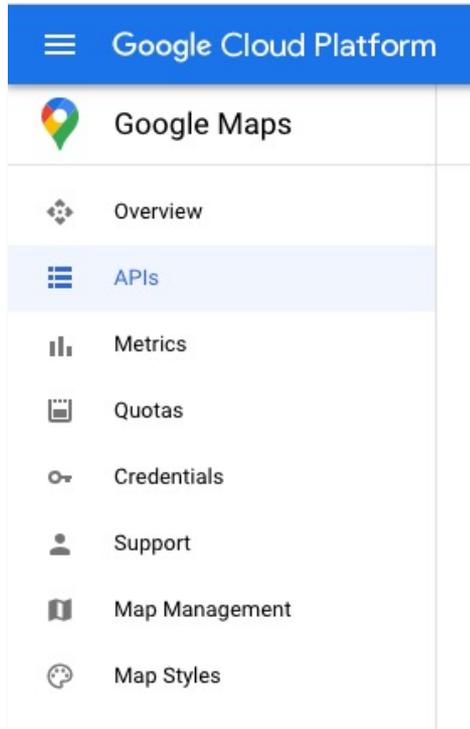


Problematic
image type:

omission of major roads (not
NRI road?)



Google Maps dataset



- Google provides a comprehensive public **API** for Google Maps
 - The parameters include centroid coordinates, layers (e.g., road) and physical scale (selected as $0.5 \times 0.5 \text{ miles}^2$ to match the NRI dataset)
- Our initial sample consisted of **40k random coordinates** of the contiguous U.S. territory matching the NRI sample



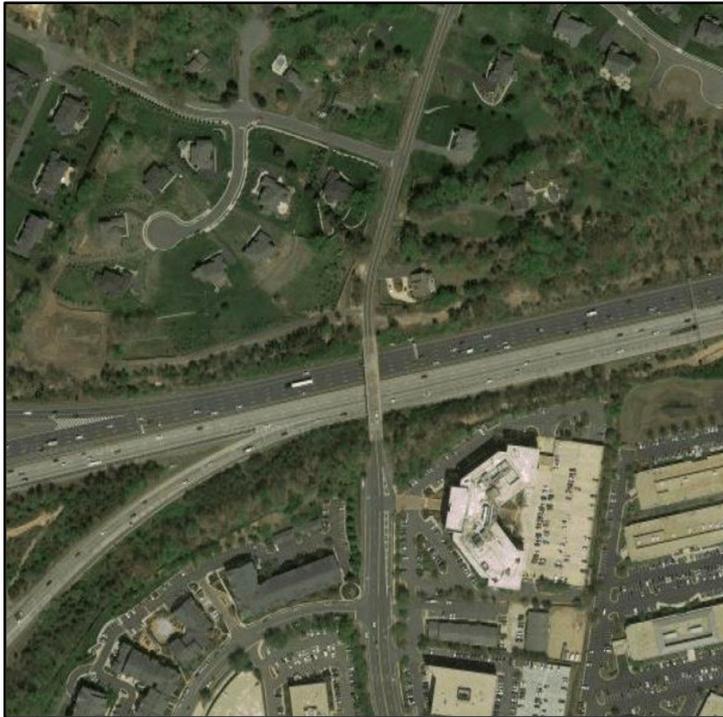
- Though generally accurate, certain image pairs do contain certain **annotation errors**

40k image pairs
from Google

Human verification

Training
dataset

Example – Image *discarded* since Google created a road that doesn't exist



Shortcomings of the training dataset

Treatment of minor roads

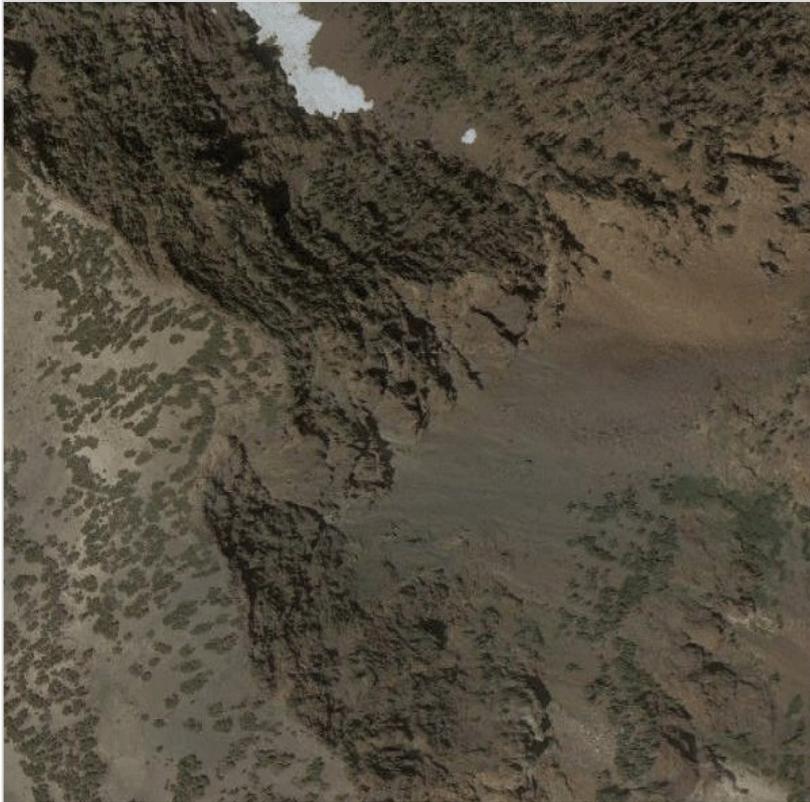
Google is inconsistent with its treatment of **minor roads** (e.g., driveways, farm access roads, parking aisles).



Shortcomings of the training dataset

Potential class imbalance

Potential **class imbalance**: there are many satellite images with no roads whatsoever.



III. Training

Modeling overview

Stage 1

Dataset for training

- NRI 5k images
(4 states)

Model

- UNet

Stage 2

Dataset for training

- Google 30k images
(49 states)

Models

- UNet
- AD-LinkNet
- GLNet

Selected methods

- Model per land use type
- Transfer learning
- Hyperparameter optimization

Datasets

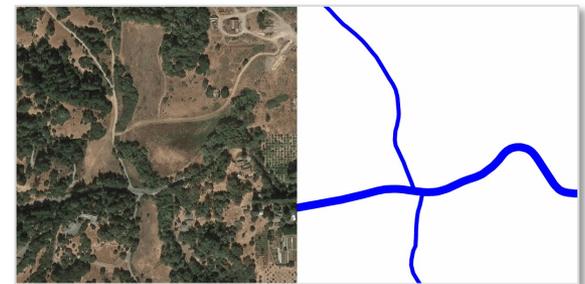
- **Original NRI dataset (4,979 image pairs)**

- IA: 1644, FL: 1165, OR: 672, ND: 1498

- **Google Maps: (31,981 image pairs)**

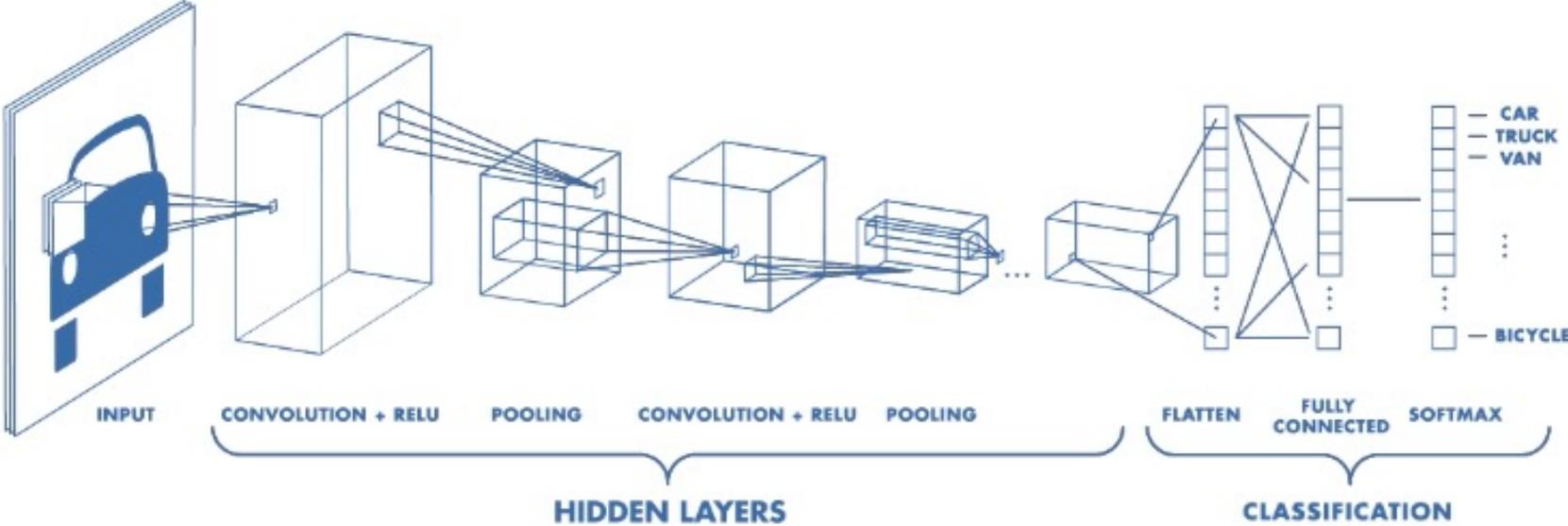
- Random coordinates across contiguous U.S. (49 states). As such, includes road-free locations.
- Filtered from original 38,641 images via visual inspection

- **NRI time series dataset (size TBD)**



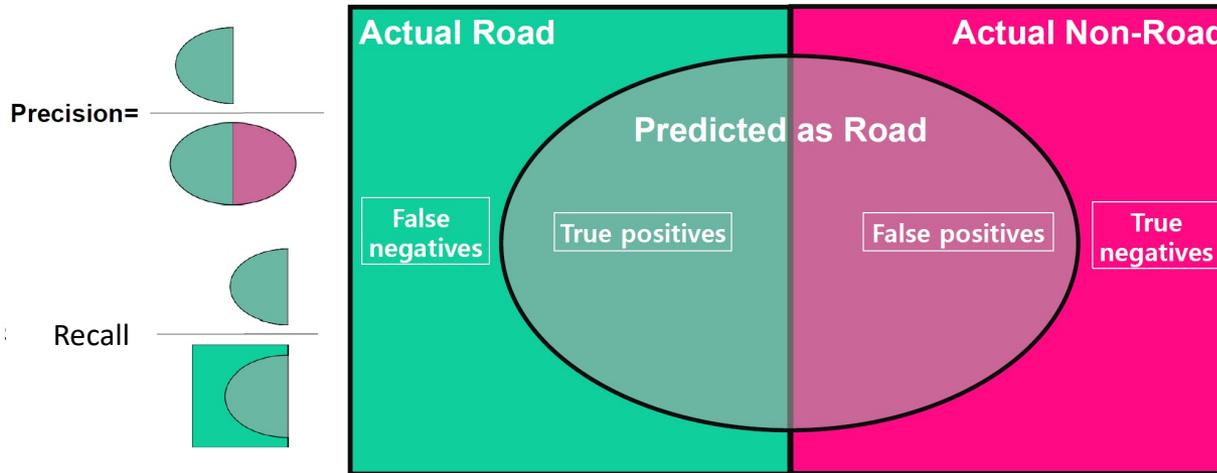
Models

Classical Convolutional Neural Network structure



Loss function

- We use pixel-level **dice loss** (i.e., $1 - \text{dice score}$) to measure the estimation and prediction performance

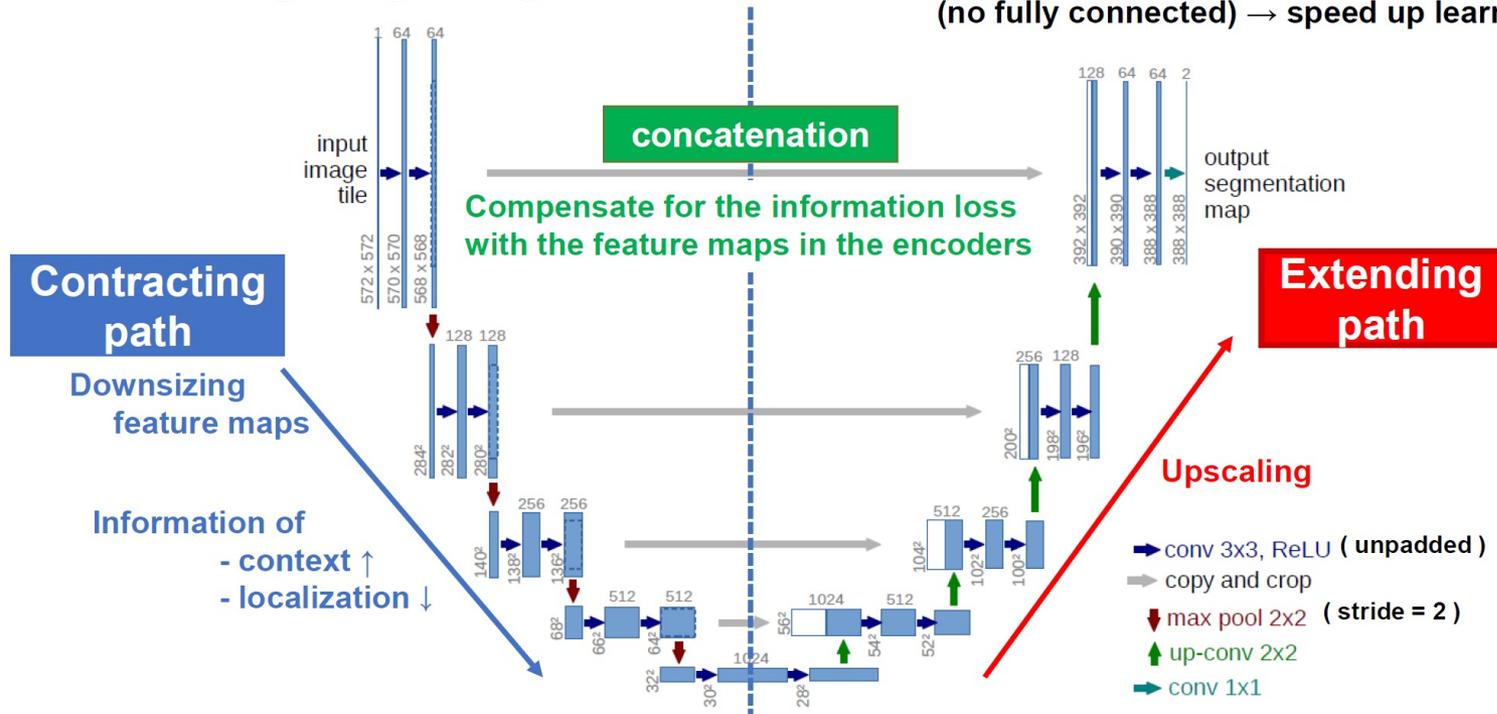


$$\text{Dice Score} = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}} \text{ is between 0 and 1}$$

U-Net

- Contracting – Expanding + Concatenation

Only convolutional and max pooling layers (no fully connected) → speed up learning



- Winner of 2015 ISBI challenge for biomedical segmentation
- The architecture looks like a ‘U’ shape
- Left: encoder; Right decoder

- Pixel-wise Prediction
- Image in; segmentation out
- Requires less training images
- Reduce overfitting by design

AD-LinkNet

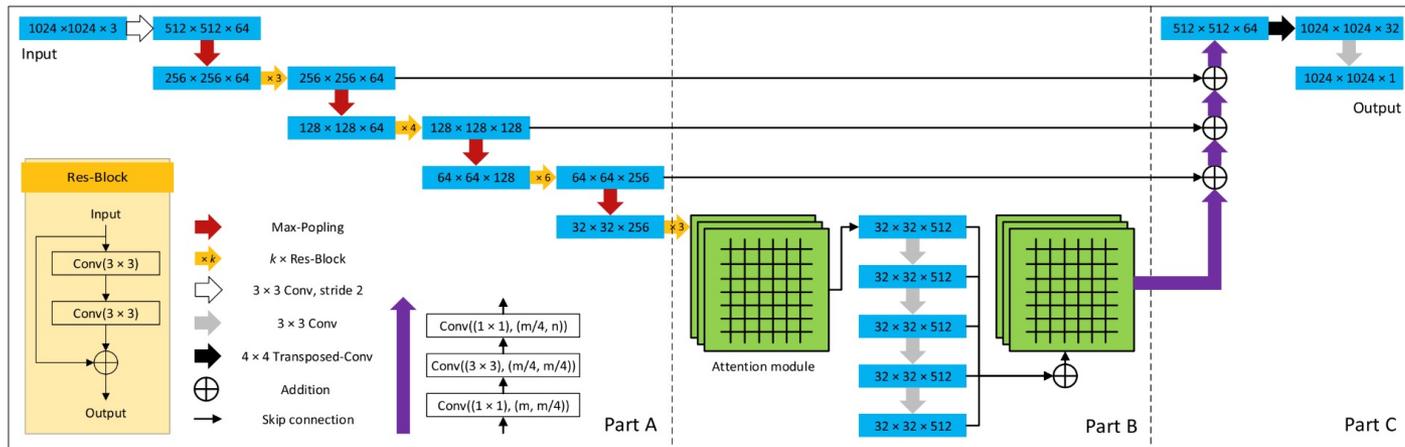


FIGURE 2. The structure diagram of AD-LinkNet.

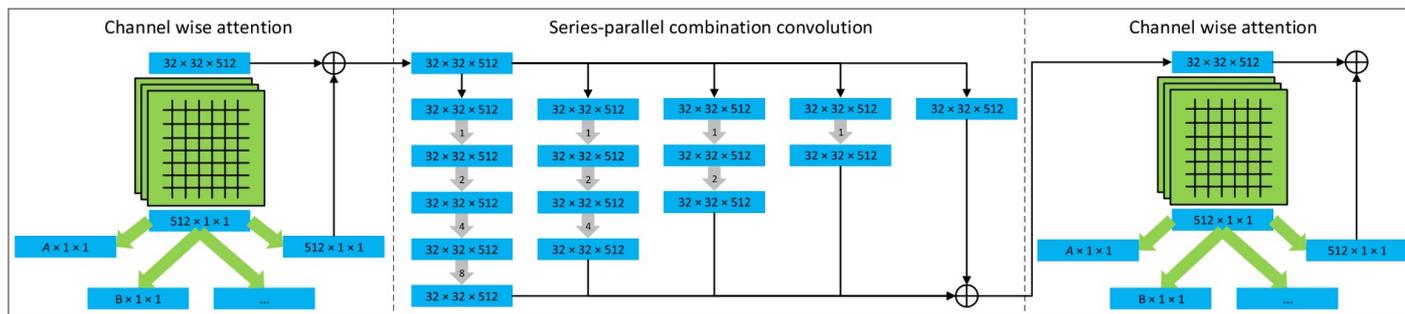
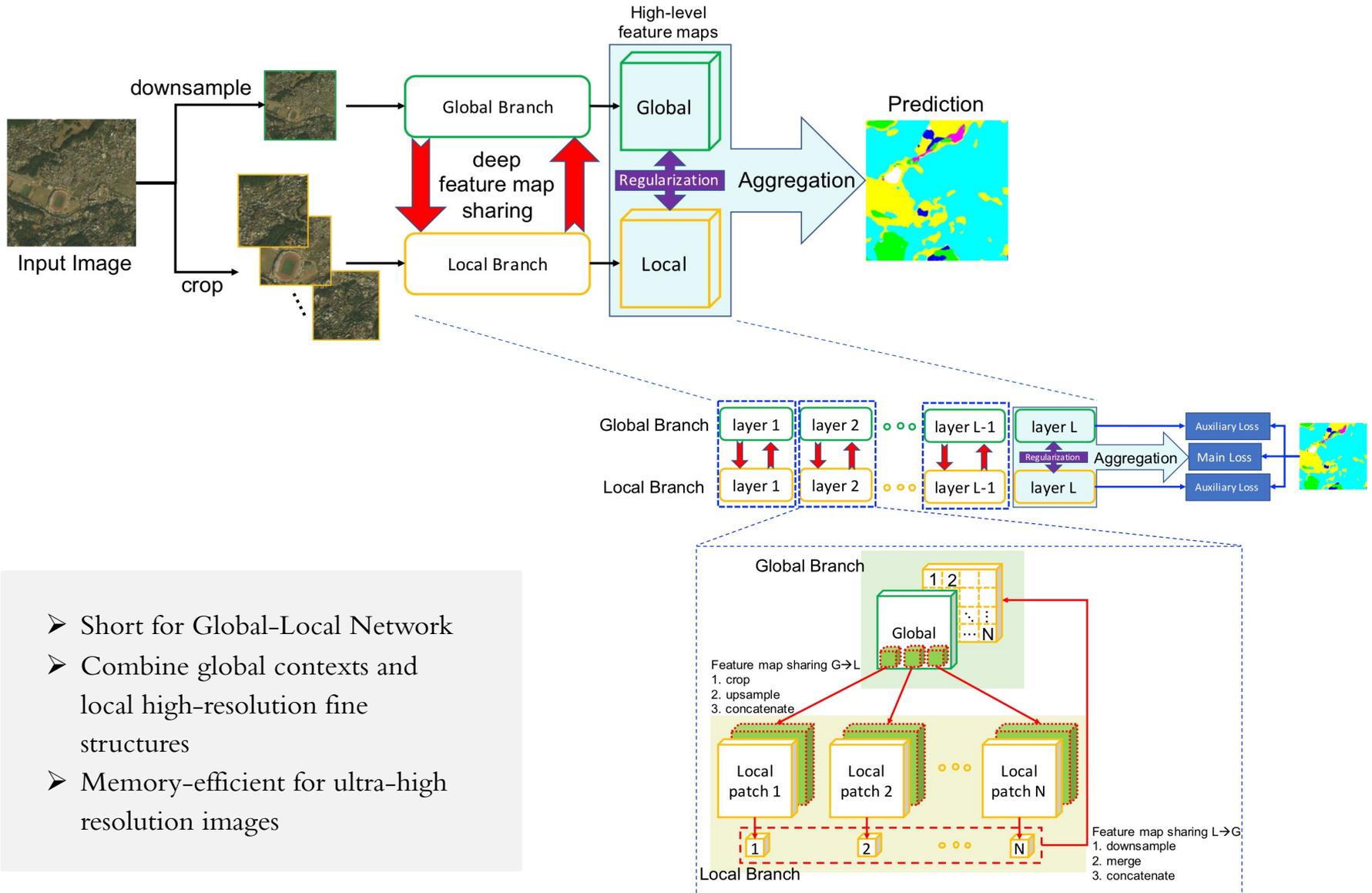


FIGURE 3. Schematic diagram of the AD-LinkNet central part.

- Winner of CVPR's 2018 DeepGlobe road extraction competition
- Short for attention dilation-Linknet
- Serial parallel combination dilated convolution
- Channel-wise attention mechanism

GLNet



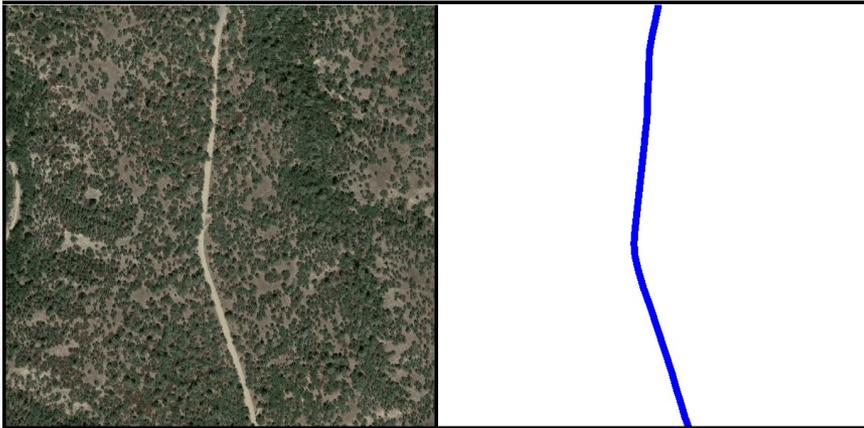
- Short for Global-Local Network
- Combine global contexts and local high-resolution fine structures
- Memory-efficient for ultra-high resolution images

Methods

Build a model per land use type

- To improve model performance, we classified the images (as either **rural** or **urban**) by land use types and then trained a model on each of the two sets of images.

Rural



Urban



Image classification | Google dataset

- We classified an image as “rural” or “urban” based on the Cropland Data Layer (CDL), which assigns land use categories to 30-meter pixels.
- If $\geq 20\%$ of the CDL pixels for the $\approx 0.5 \times 0.5 \text{ mi}^2$ area captured by a Google satellite image is “developed” land, we label it “**urban.**” Otherwise, the image is “**rural.**”
- Urban ratio (UR) = (number of developed land CDL pixels) / (total CDL pixels)
 - $UR > 0.2 \rightarrow$ urban type: 7.9% of total dataset (2526 images)
 - $UR \leq 0.2 \rightarrow$ rural type : 92.8% of total dataset

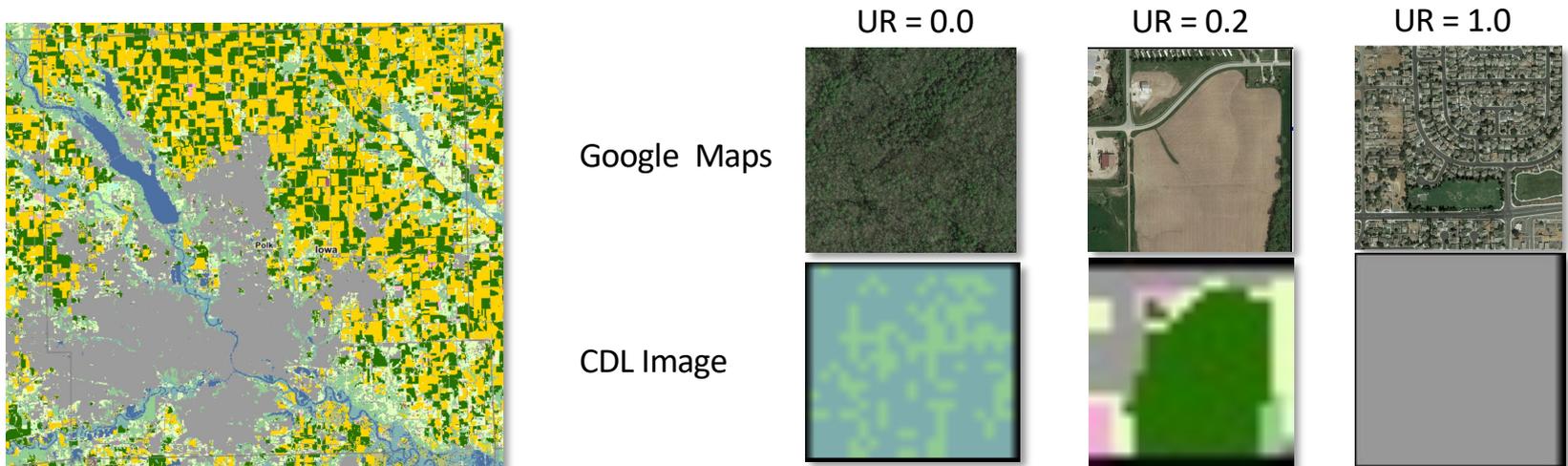


Image classification | Original NRI dataset

- The metadata for each image includes the **3 most representative land use types**. (*Repeated land use types allowed for a single image.*)
- We classify an image as “**urban**” if either
 1. one of its 3 land use types is “large urban,” or
 2. the list of 3 types consists entirely of “small urban” or “public road.”
- Otherwise, we classify each image as “**rural**”

[Public Road, **Large Urban**, Small Urban] [**Public Road**, **Small Urban**, **Small Urban**] [Cropland, Cropland, Public Road]



[Urban]



[Urban]

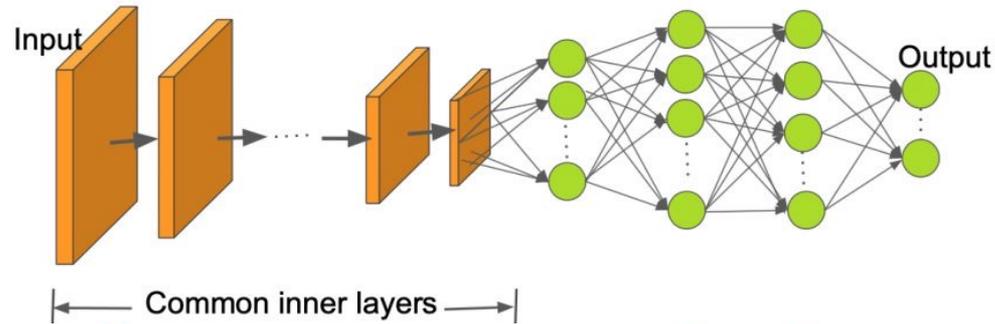


[Rural]

Transfer learning

ImageNet
(1M images)

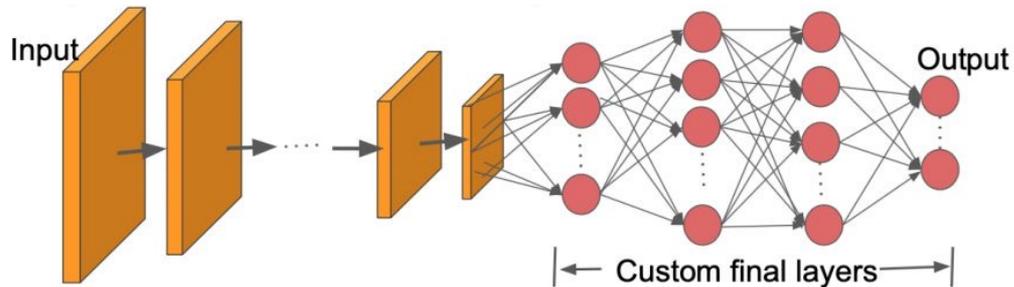
Pretrained
Model



Classification:
Cat, dog, boat,
chair, ...

All 30k
Google
Maps images

Custom
Model



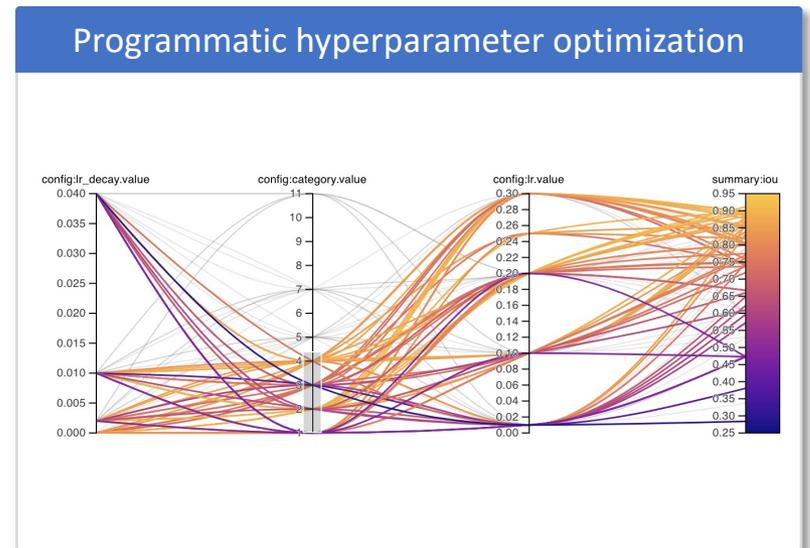
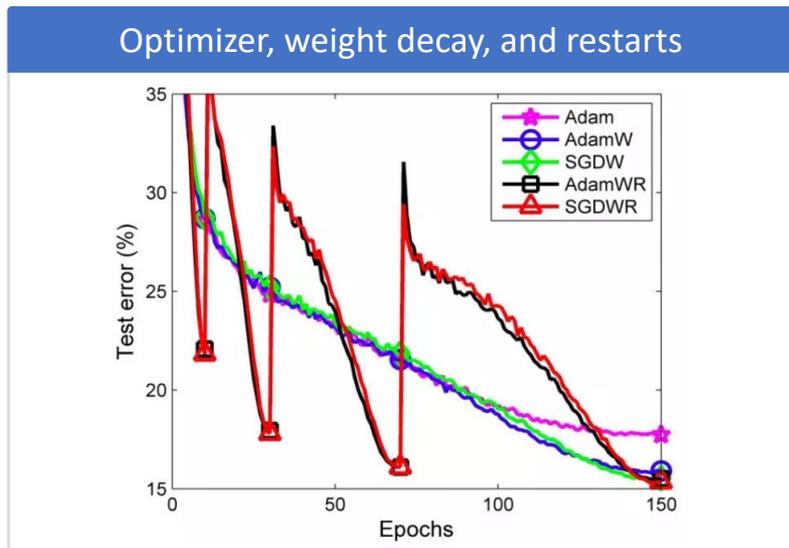
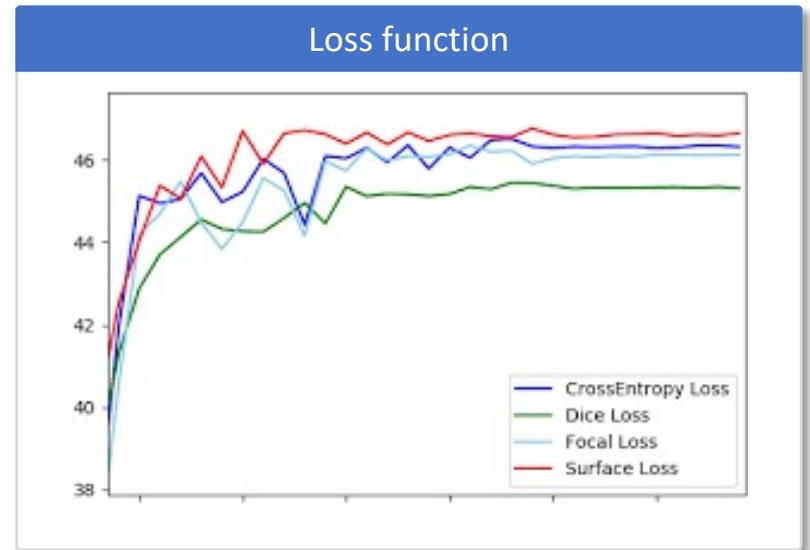
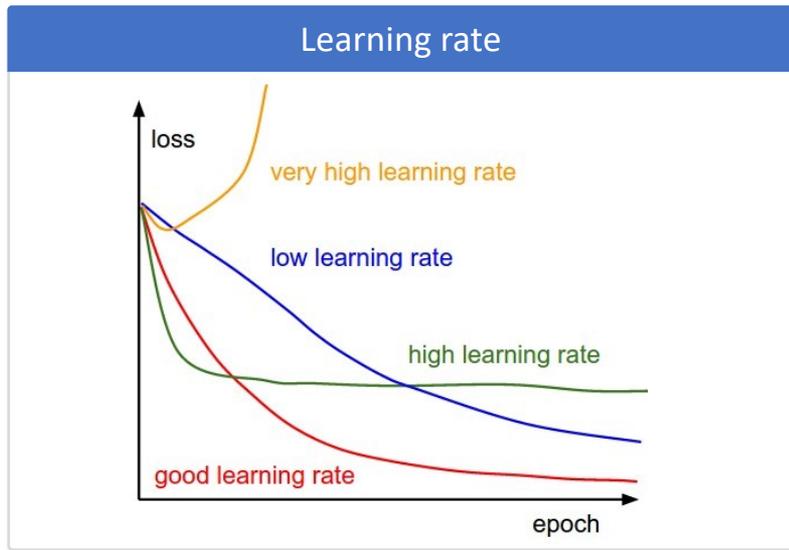
Road
annotation

Only the
"urban"
Google images

"Top-level" model: this model has the same architecture as the model immediately above. Additionally, we initialize this model's weights with the previous model's fitted weights.

Road
annotation

Hyperparameter optimization

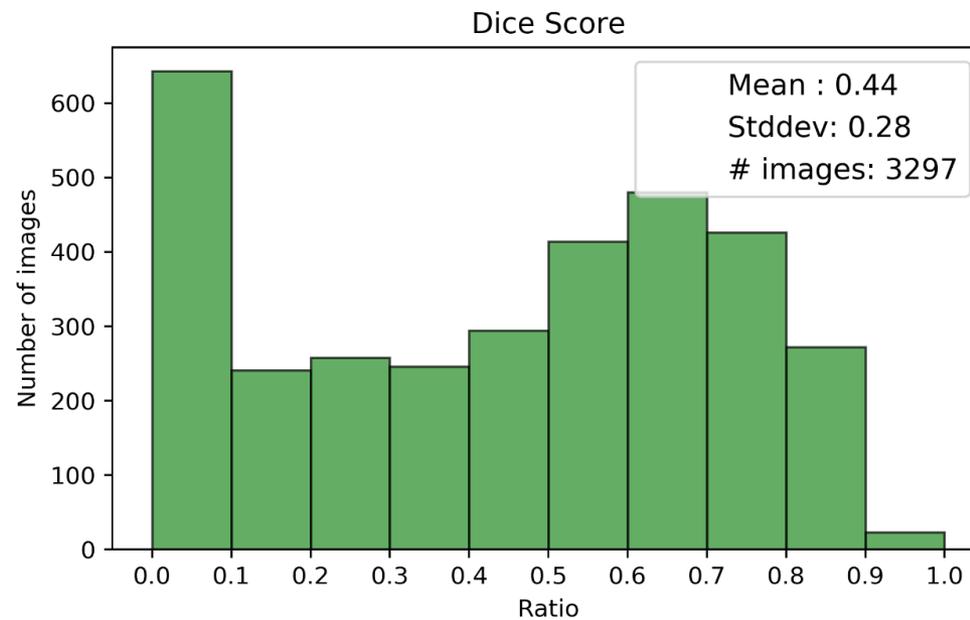


Results

Stage 1

Stage 1 | Original NRI dataset

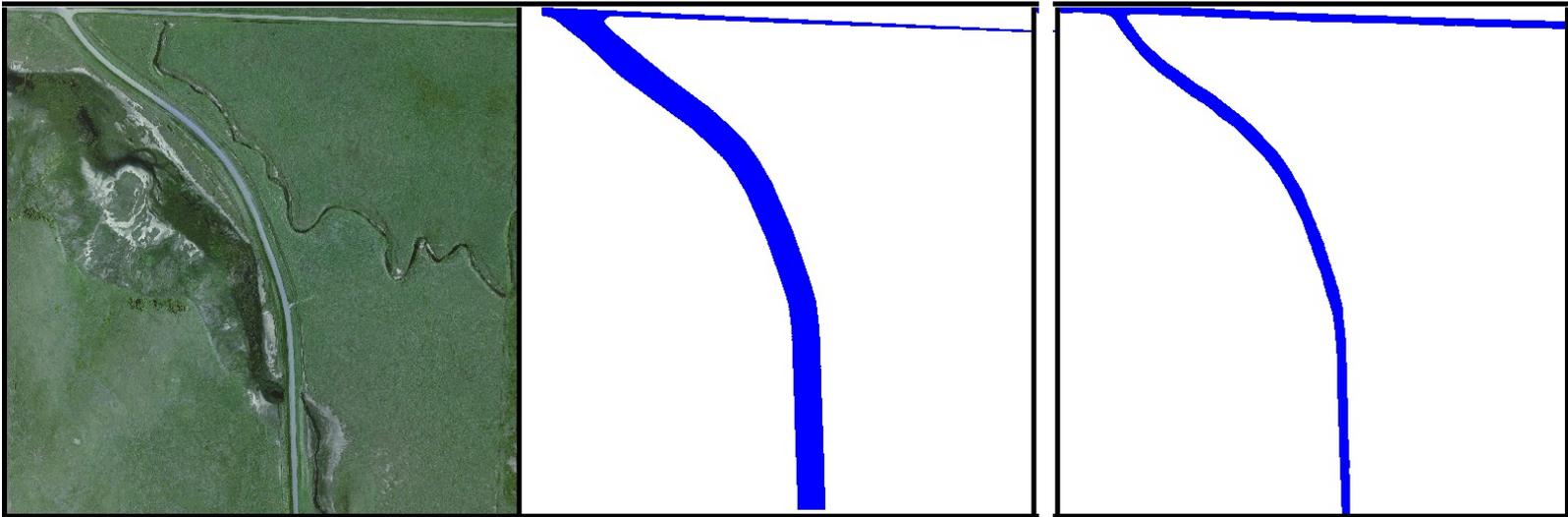
	Rural				Urban				Total			
Model	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall
U-Net	0.45	0.28	0.45	0.50	0.35	0.21	0.36	0.28	0.44	0.28	0.43	0.49



Original NRI dataset | Example 1 (rural)

Ground truth

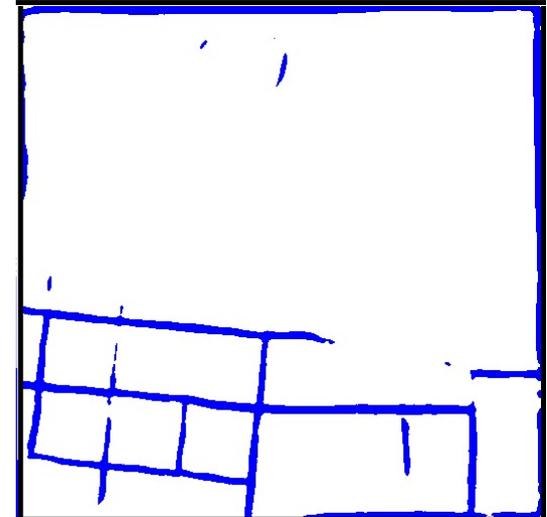
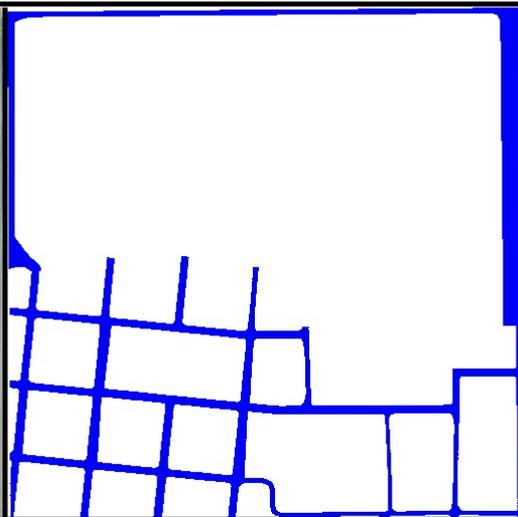
Prediction



Original NRI dataset | Example 2 (semi-developed)

Ground truth

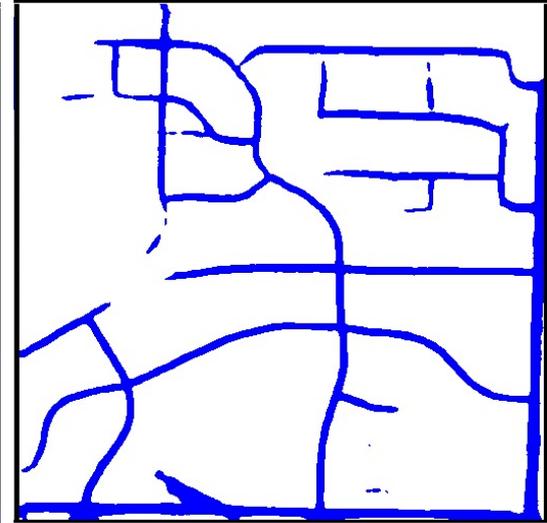
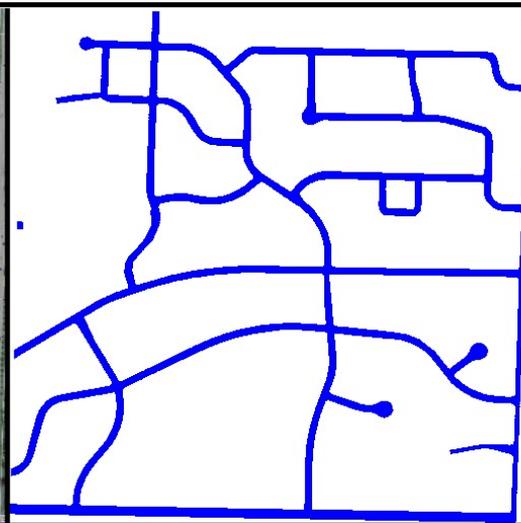
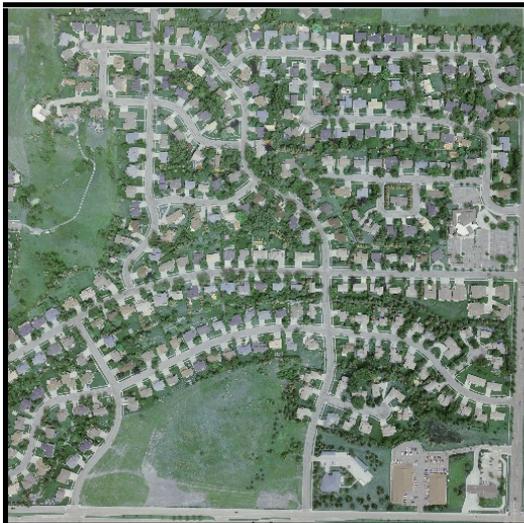
Prediction



Original NRI dataset | Example 3 (urban)

Ground truth

Prediction

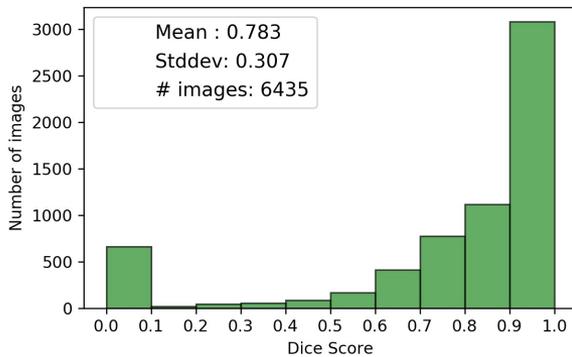


Stage 2

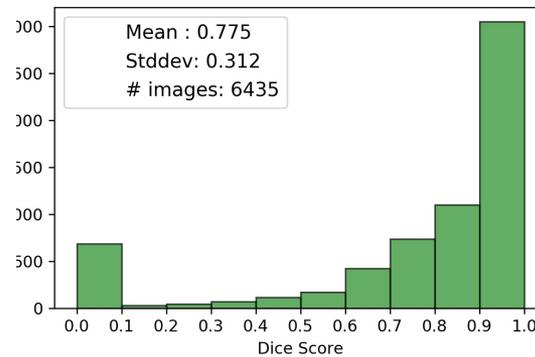
Stage 2 | Google dataset

	Rural				Urban				Total			
Model	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall
AD-LinkNet (TL*)	0.79	0.32	0.86	0.83	0.73	0.14	0.74	0.75	0.78	0.31	0.85	0.82
U-Net (TL)	0.78	0.32	0.84	0.84	0.72	0.15	0.74	0.74	0.78	0.31	0.83	0.83
GLNet (TL)	0.73	0.35	0.88	0.75	0.62	0.24	0.68	0.69	0.72	0.35	0.86	0.75

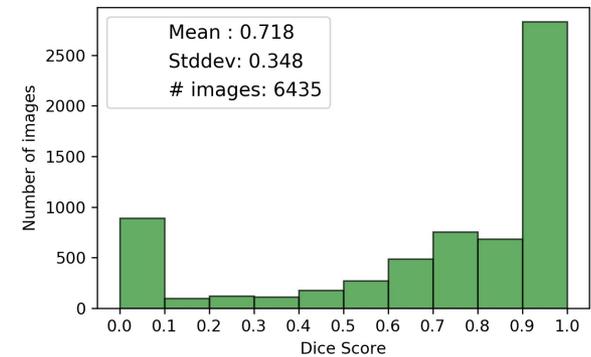
Ad-LinkNet



U-Net



GLNet

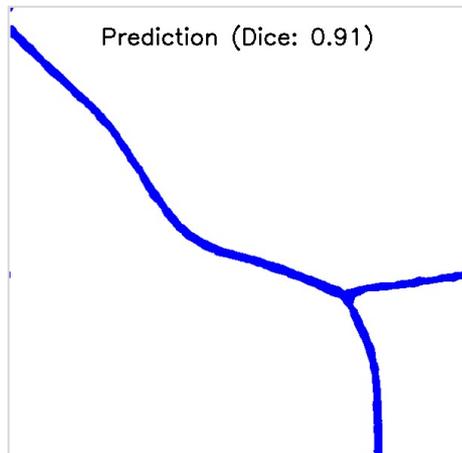


* TL = Transfer learning

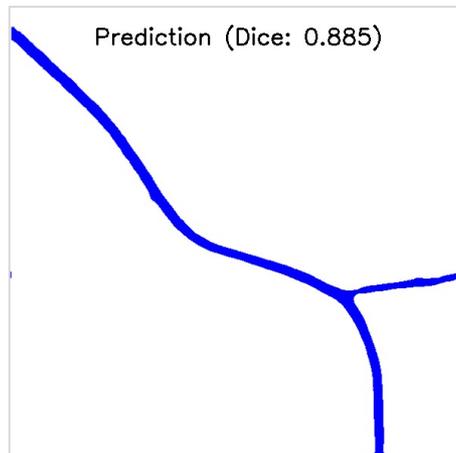
KY_0388



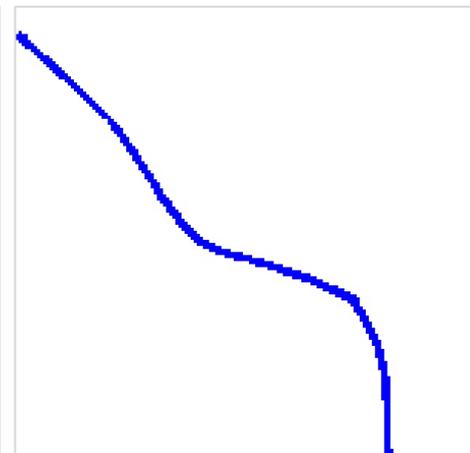
Ad-LinkNet



U-Net



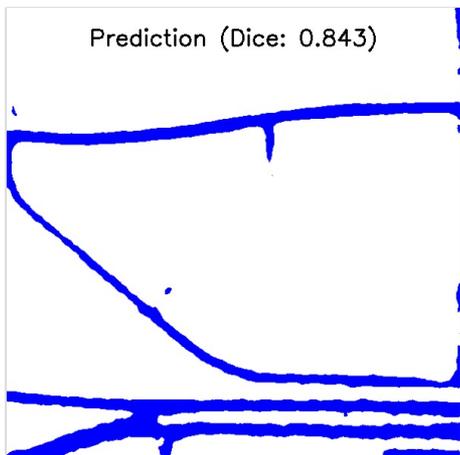
GLNet



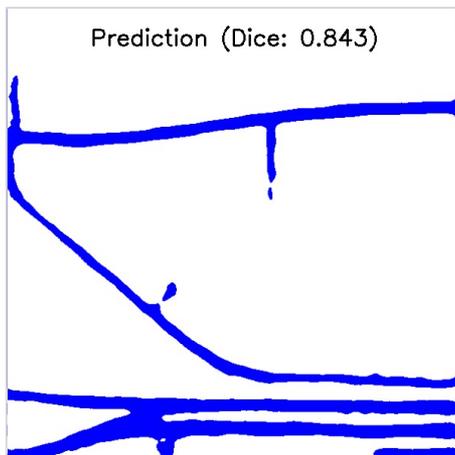
WI_0796



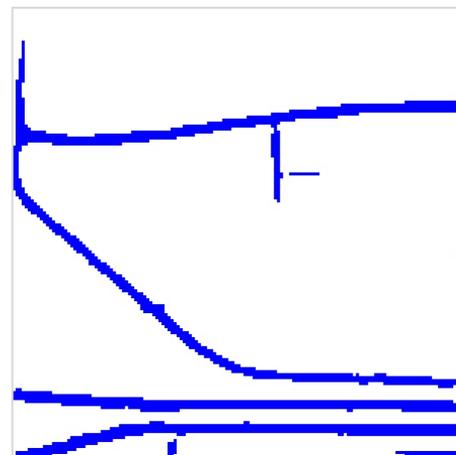
Ad-LinkNet



U-Net



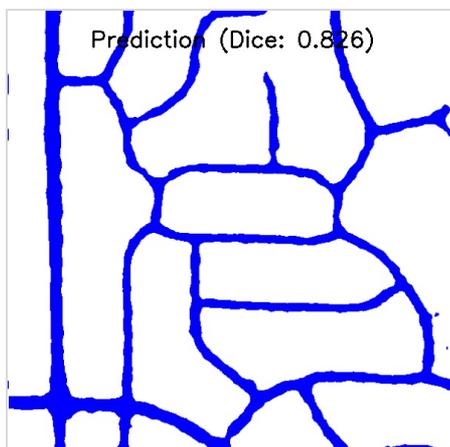
GLNet



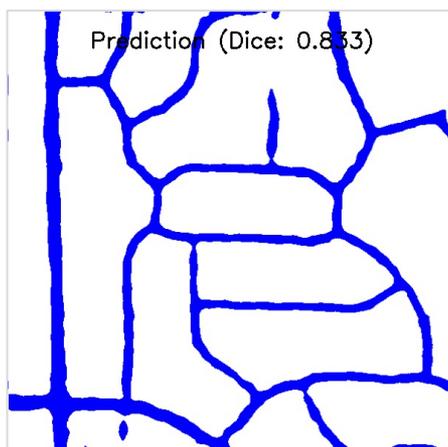
NJ_0177



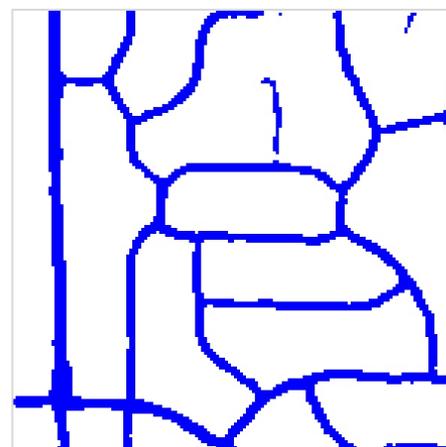
Ad-LinkNet



U-Net



GLNet



Stage 2 | Original NRI dataset

Stage 1: trained on **original NRI dataset**

Model	Rural				Urban				Total			
	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall
U-Net	0.45	0.28	0.45	0.50	0.35	0.21	0.36	0.28	0.44	0.28	0.43	0.49

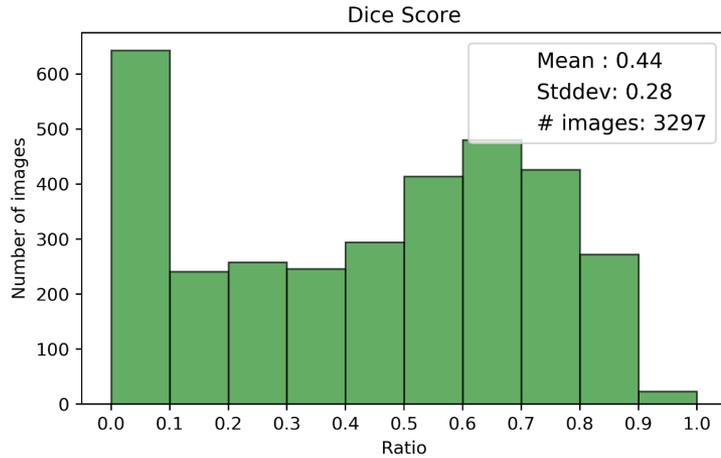
Stage 2: trained on **Google dataset**

Model	Rural				Urban				Total			
	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall	Dice	SE	Prec.	Recall
AD-LinkNet (TL*)	0.56	0.23	0.63	0.61	0.51	0.15	0.49	0.59	0.56	0.22	0.62	0.61
U-Net (TL)	0.54	0.22	0.57	0.63	0.48	0.16	0.47	0.58	0.54	0.22	0.56	0.62

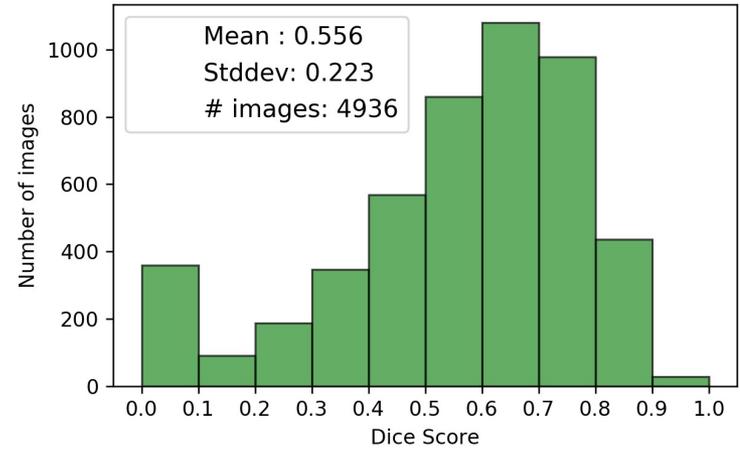
* TL = Transfer learning

Dice score histograms

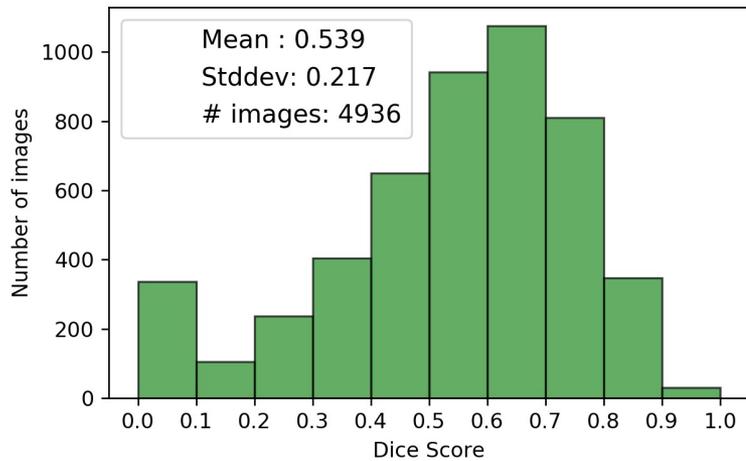
U-Net (Stage 1)



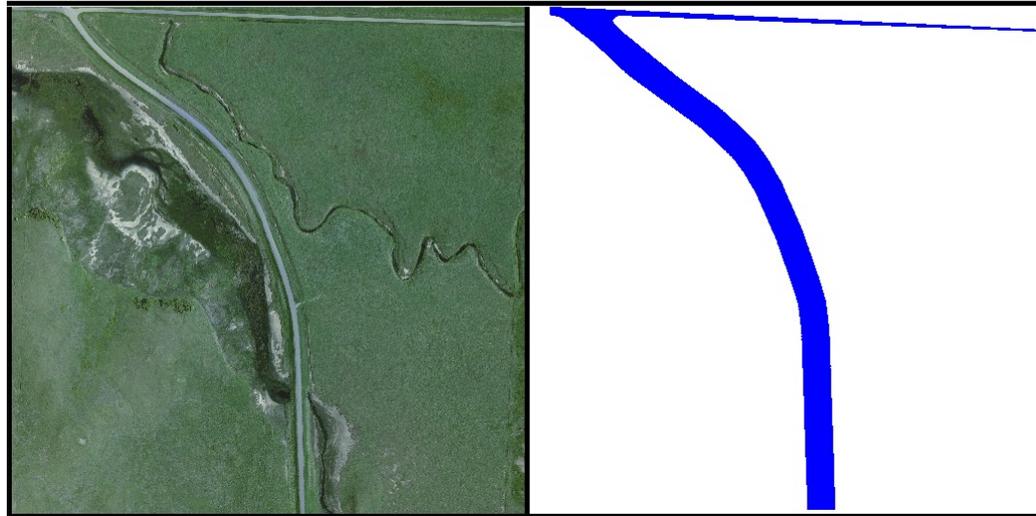
Ad-LinkNet



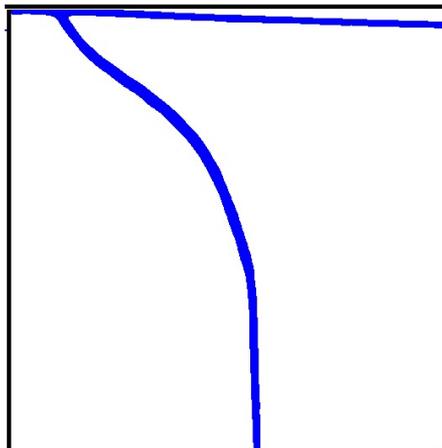
U-Net (Stage 2)



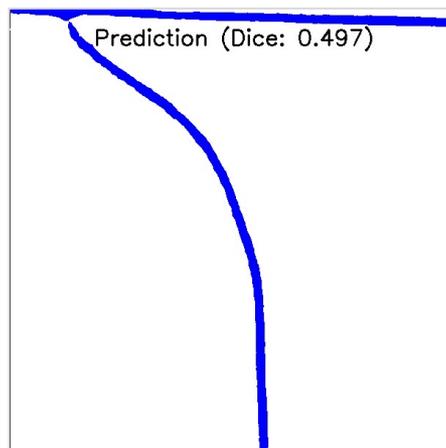
NRI dataset | Example 1 (rural)



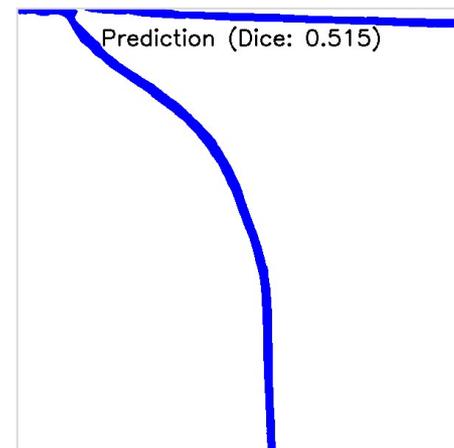
U-Net (Stage 1)



Ad-LinkNet



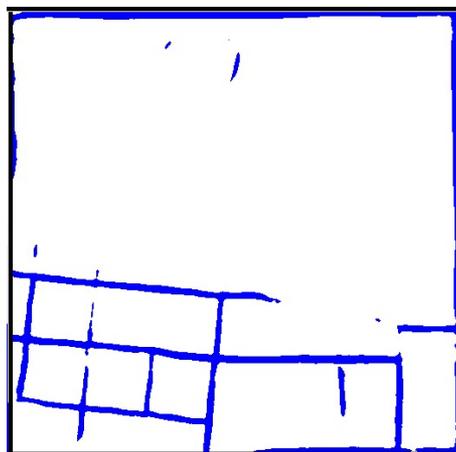
U-Net (Stage 2)



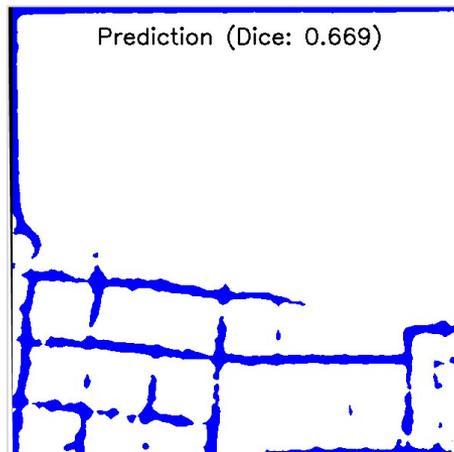
NRI dataset | Example 2 (semi-developed)



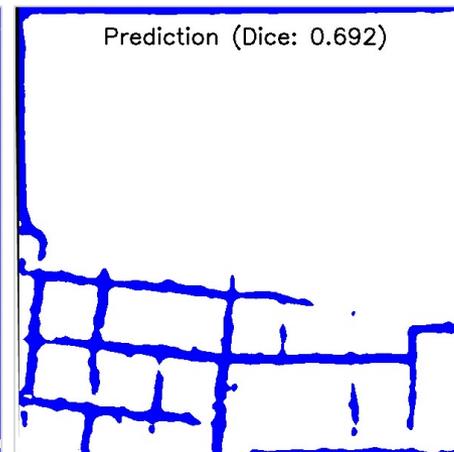
U-Net (Stage 1)



Ad-LinkNet



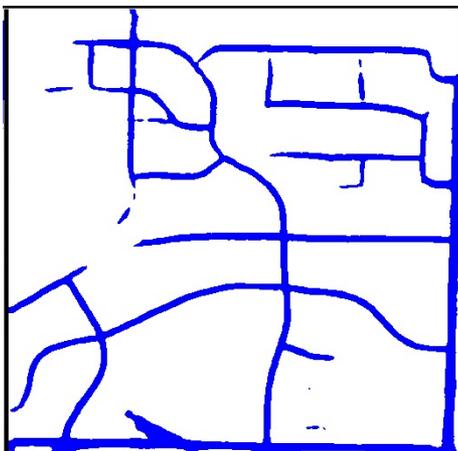
U-Net (Stage 2)



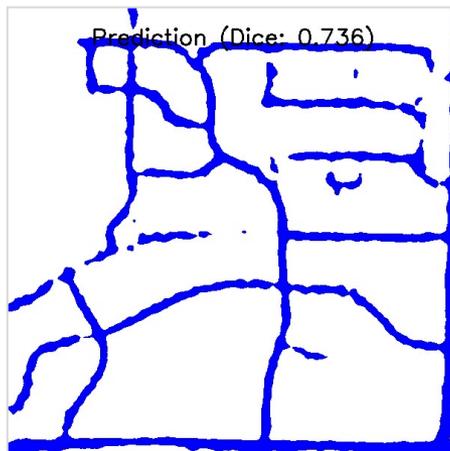
NRI dataset | Example 3 (urban)



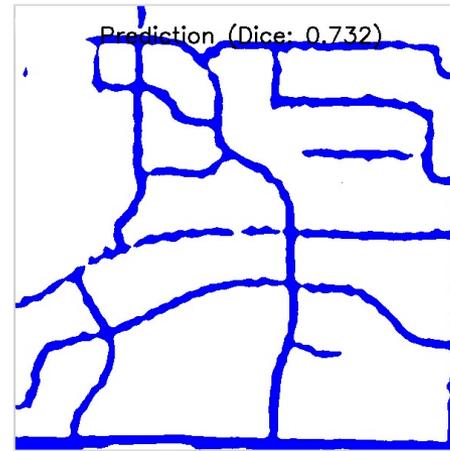
U-Net (Stage 1)



Ad-LinkNet



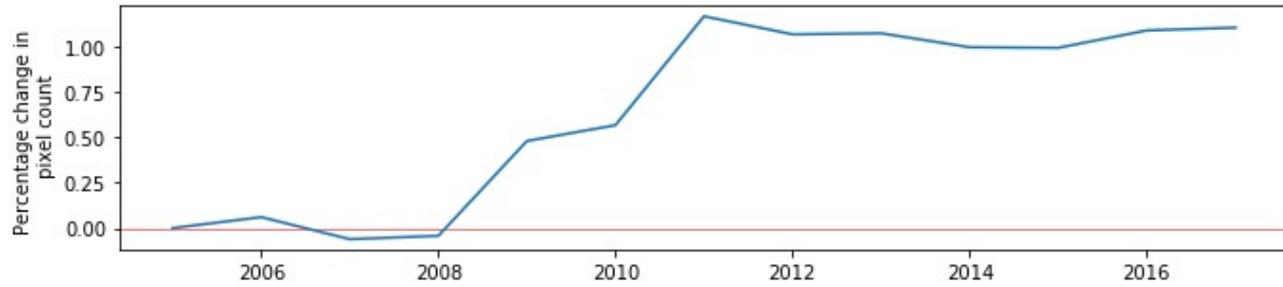
U-Net (Stage 2)



Stage 3

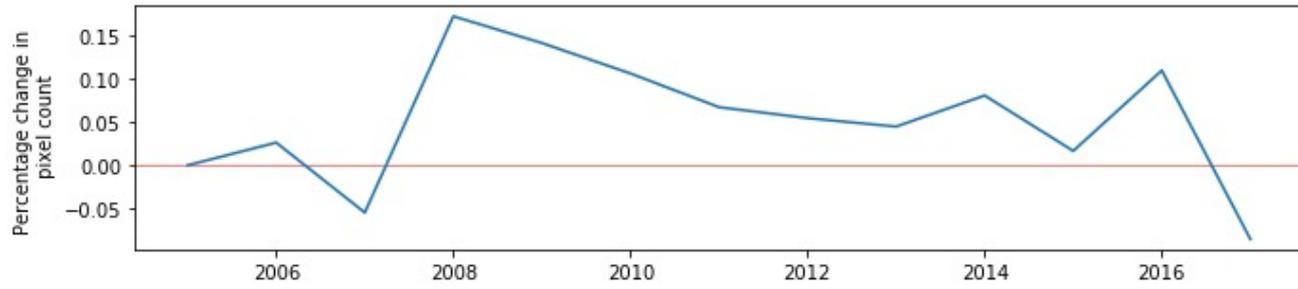
Example 1

Model: AD-LinkNet (transfer learning, rural)



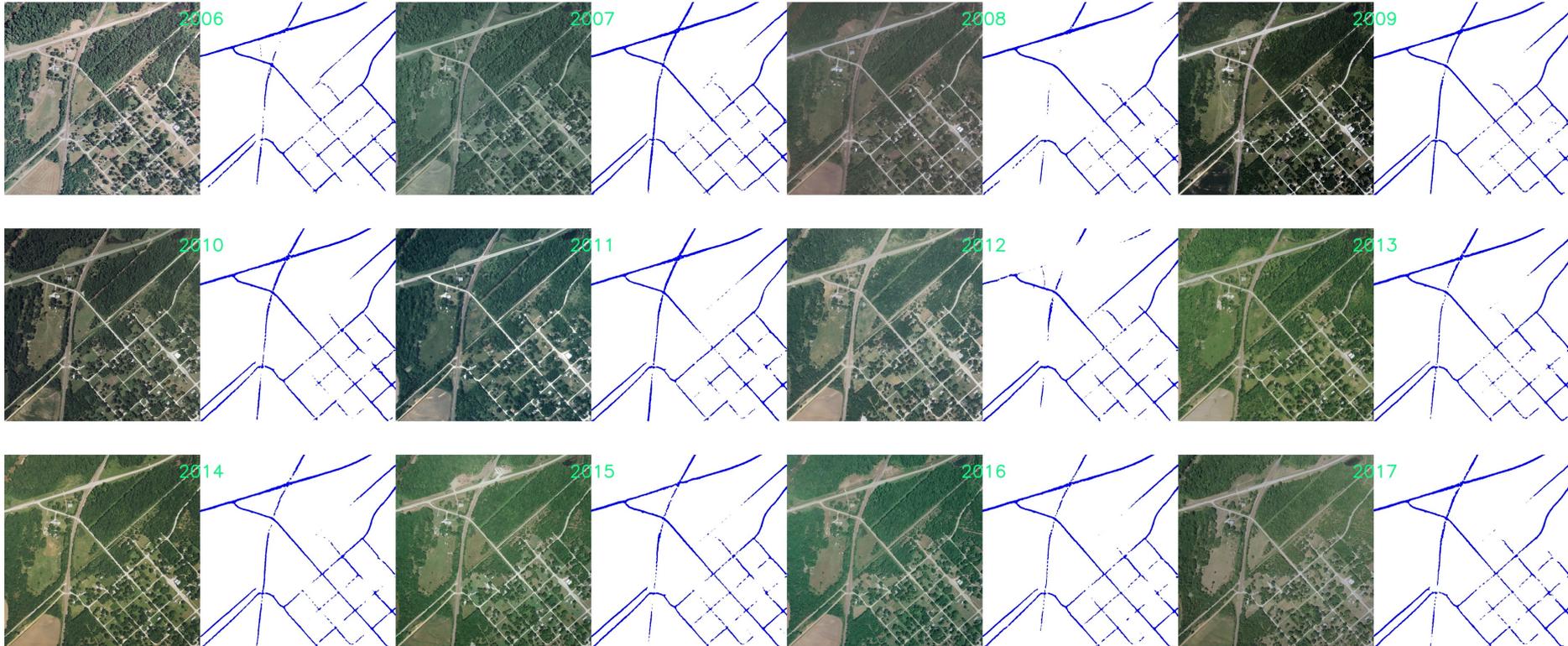
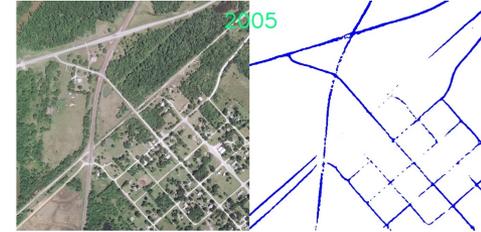
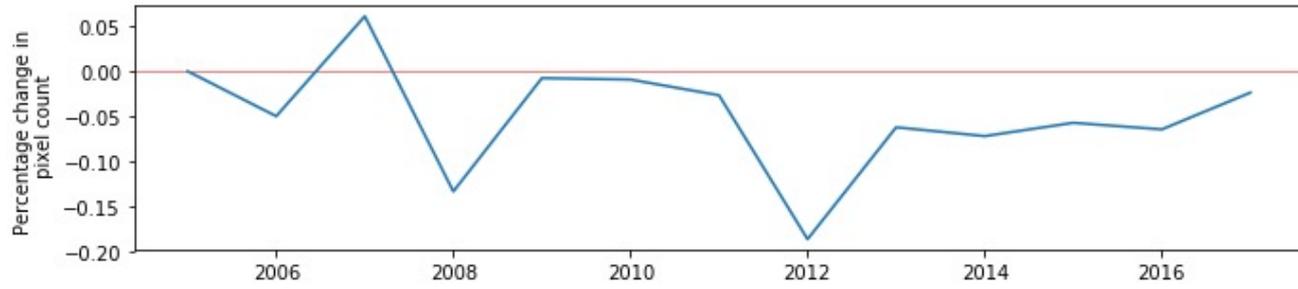
Example 2

Model: AD-LinkNet (transfer learning, rural)



Example 3

Model: AD-LinkNet (transfer learning, rural)



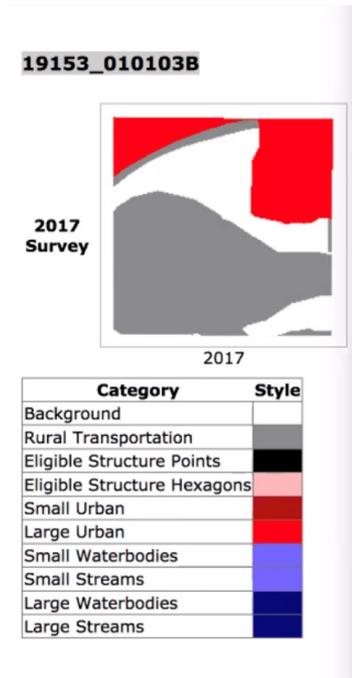
IV. Next steps

Next steps

- Determine change detection thresholds
- **Classification of NRI images by terrain type** (so we can then fit a separate model for each class)
- Conformal prediction
- Hyperparameter optimization
- Consider training on higher resolution images
- Alternate loss functions
- Post-processing
- Run models longer
- Promising tweaks to GLNet
- Deeper version of UNet

Classification of NRI images

- The pre-defined land use types in NRI, similar to CDL for Google help to advance the classification performance
- Select a representative class out of the polygons for certain types



Questions?